

# Datasheet GXHTC3

## Humidity and Temperature Sensor IC

- Ultra-low power consumption
- Full battery supply voltage range (1.62 – 5.5 V)
- Small DFN package: 2 × 2 × 0.75 mm<sup>3</sup>
- Typical accuracy: ±3 %RH and ±0.2 °C
- Fully calibrated and reflow solderable
- Power-up and measurement within 1.5ms

### Product Summary

The GXHTC3 is a digital humidity and temperature sensor designed especially for battery-driven high-volume consumer electronics applications. This sensor is strictly designed to overcome conventional limits for size, power consumption, and performance to price ratio in order to fulfill current and future requirements. GXCAS offers a complete sensor system on a single chip, consisting of a capacitive humidity sensor, a bandgap temperature sensor, analog and digital signal processing, A/D converter, calibration data memory, and a digital communication interface supporting I<sup>2</sup>C Fast Mode Plus. The small 2 × 2 × 0.75 mm<sup>3</sup> DFN package enables applications in even the most limited of spaces.

The sensor covers a humidity measurement range of 0 to 100 %RH and a temperature measurement range of - 45°C to +130 °C with a typical accuracy of ±2 %RH and ±0.2°C. The broad supply voltage of 1.62 V to 3.3 V and an energy budget below 1 μJ per measurement make the GXHTC3 suitable for mobile or wireless applications powered by batteries. With the industry-proven quality and reliability of GXCAS humidity and temperature sensors and constant accuracy over a large measurement range, the GXHTC3 offers best performance-to-price ratio. Tape and reel packaging together with suitability for standard SMD assembly make the GXHTC3 predestined for high-volume applications.



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### Block diagram

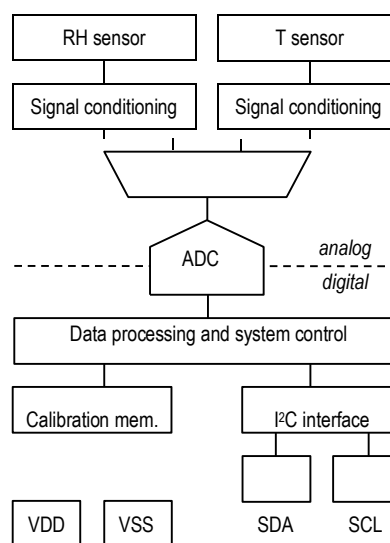


Figure 1 Functional block diagram of the GXHTC3.

# 1 Humidity and Temperature Sensor Specifications

Every GXHTC3 is individually tested and calibrated and is identifiable by its unique serial number. The serial number is stored in an unchangeable OTP memory.

For the calibration, GXCAS uses transfer standards, which are subject to a scheduled calibration procedure.

## Relative Humidity

| Parameter                       | Condition             | Value        | Unit  |
|---------------------------------|-----------------------|--------------|-------|
| Accuracy tolerance <sup>1</sup> | Typ.                  | ±3.0         | %RH   |
|                                 | Max.                  | see Figure 2 | %RH   |
| Repeatability                   | -                     | 0.1          | %RH   |
| Resolution                      | -                     | 0.01         | %RH   |
| Hysteresis                      | -                     | ±1           | %RH   |
| Specified range                 | extended <sup>5</sup> | 0 to 100     | %RH   |
| Response time                   | τ 63%                 | 8            | s     |
| Long-term drift                 | Typ.                  | <0.25        | %RH/y |

Table 1 Humidity sensor specifications.

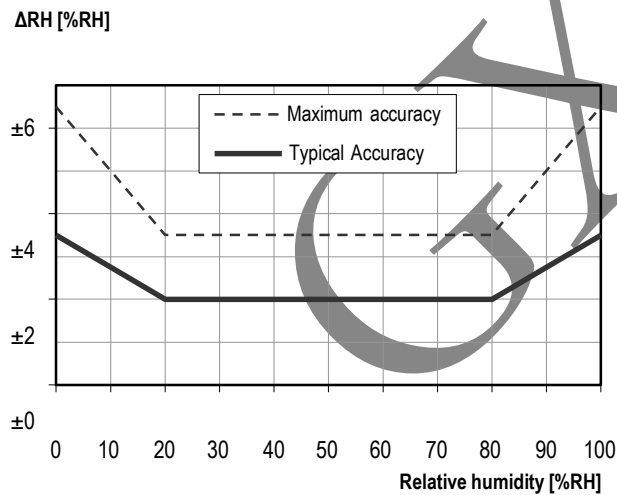


Figure 2 Typical and maximal tolerance for relative humidity in %RH at 25 °C.

## Temperature

| Parameter                       | Condition | Value        | Unit |
|---------------------------------|-----------|--------------|------|
| Accuracy tolerance <sup>1</sup> | Typ.      | ±0.2         | °C   |
|                                 | Max.      | see Figure 3 | °C   |
| Repeatability <sup>2</sup>      | -         | 0.1          | °C   |
| Resolution <sup>3</sup>         | -         | 0.01         | °C   |
| Specified range <sup>4</sup>    | -         | -40 to +125  | °C   |
| Response time <sup>8</sup>      | τ 63%     | <5 to 30     | s    |
| Long-term drift <sup>9</sup>    | Typ.      | <0.02        | °C/y |

Table 2 Temperature sensor specifications.

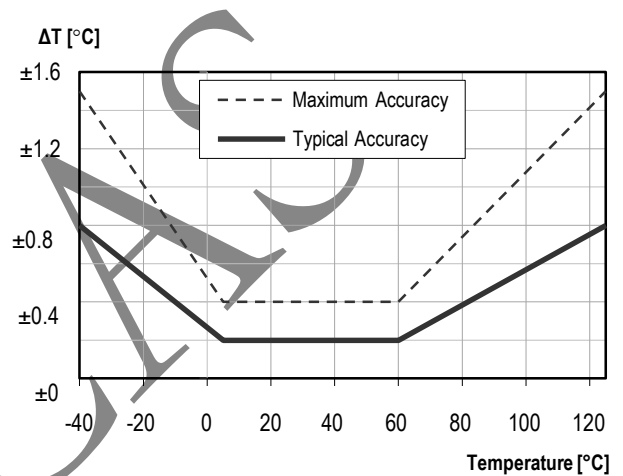


Figure 3 Typical and maximal tolerance for temperature sensor in °C.

## 1.1 Recommended Operating Conditions

The sensor performs best when operated within the recommended normal temperature and humidity range of 5 –60 °C and 20 – 80 %RH, respectively. Long-term exposure to conditions outside the normal range, especially at high humidity, may temporarily offset the RH signal (e.g. +3%RH after 60h at >80%RH). After returning to normal temperature and humidity range the sensor will slowly come back to its calibration state by itself. Prolonged exposure to extreme conditions may accelerate ageing.

To ensure stable operation of the humidity sensor, the conditions described in the document “GXHTxx Assembly of SMD Packages”, section “Storage and Handling Instructions” regarding exposure to volatile organic compounds have to be met. Please note as well that this does apply not only to transportation and manufacturing, but also to operation of the GXHTC3.

## 2 Electrical Specifications

### 2.1 Electrical Characteristics

Default conditions of 25 °C and 3.3 V supply voltage apply to values in the table below, unless otherwise stated.

| Parameter                | Symbol           | Conditions          | Min                 | Typ. | Max                  | Units  | Comments  |  |
|--------------------------|------------------|---------------------|---------------------|------|----------------------|--|---|--|
| Supply voltage           | V <sub>DD</sub>  |                     | 1.62                | 3.3  | 5.5                  | V  | -   |  |
| Power-up/down level      | V <sub>POR</sub> | Static power supply | 1.28                | 1.4  | 1.55                 | V  | -   |  |
| Supply current           | I <sub>DD</sub>  | Idle state          | -                   | 45   | 70                   | μA   | After power-up the sensor remains in the idle state unless a sleep command is issued or other data transmission is active |  |
|                          |                  | Sleep Mode          | -                   | 0.3  | 0.6                  | μA   | When in sleep mode, the sensor requires a dedicated wake-up command to enable further I <sup>2</sup> C communication      |  |
|                          |                  | Measurement         | Normal Mode         | -    | 430                  | 900  | μA  | Average current consumption while the sensor is measuring                          |
|                          |                  |                     | Low Power M.        | -    | 270                  | 570  | μA  |  |
|                          |                  | Average             | Normal Mode         | -    | 4.9                  | -  | μA  | Average current consumption (continuous operation with one measurement per second) |
| Low Power M.             | -                |                     | 0.5                 | -    | μA                   | Average current consumption (continuous operation with one measurement per second) |   |  |
| Low level input voltage  | V <sub>IL</sub>  | -                   | -                   | -    | 0.42 V <sub>DD</sub> | V  | -   |  |
| High level input voltage | V <sub>IH</sub>  | -                   | 0.7 V <sub>DD</sub> | -    | -                    | V  | -   |  |
| Low level output voltage | V <sub>OL</sub>  | 3 mA sink current   | -                   | -    | 0.2 V <sub>DD</sub>  | V  | -   |  |

Tabl 3 Electrical specifications.

## 2.2 Absolute Maximum Ratings

Stress levels beyond the limits listed in Table 4 may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these conditions cannot be guaranteed. Exposure to the absolute maximum rating conditions for extended periods may affect the reliability of the device. Parameters are only tested each at a time.

| Parameter                                   | Rating         |
|---|----------------|
| Supply voltage, $V_{DD}$                    | -0.3 to +5.5V  |
| Operating temperature range                 | -45 to +130°C  |
| Storage temperature range <sup>10</sup>     | -45 to +130 °C |
| ESD HBM (human body model) <sup>11</sup>    | -2 to 2 kV     |
| ESD CDM (change device model) <sup>12</sup> | -500 to 500 V  |
| Latch up, JEESD78 Class II, 125°C           | -100 to 100 mA |

**Table 4** Absolute maximum ratings.

## 3 Timing Specifications

### 3.1 Sensor System Timings

Default conditions of 25 °C and 3.3 V supply voltage apply to values the table below, unless otherwise stated. Max. values are measured at -40 °C.

| Parameter            | Symbol     | Conditions                              | Min.         | Typ. | Max. | Units   | Comments   |   |
|----------------------|------------|---|--------------|------|------|---------|--|---|
| Power-up time        | $t_{PU}$   | After hard reset, $V_{DD} \geq V_{POR}$ | -            | 180  | 240  | $\mu s$ | Time between $V_{DD}$ reaching $V_{PU}$ and sensor entering the idle state |   |
| Soft reset time      | $t_{SR}$   | After soft reset.                       | -            | 180  | 240  | $\mu s$ | Time between ACK of soft reset command and sensor entering the idle state  |   |
| Measurement duration | $t_{MEAS}$ | Average                                 | Normal Mode  | -    | 10.8 | 12.1    | ms   | Duration for a humidity and temperature measurement |
|                      |            |   | Low Power M. | -    | 0.7  | 0.8     |  |   |

**Table 5** System timing specifications.

<sup>10</sup> The recommended storage temperature range is 10-50°C. Please consult the document "GXHTxx Handling Instructions" for more information.

<sup>11</sup> According to ANSI/ESDA/JEDEC JS-001-2014; AEC-Q100-002.

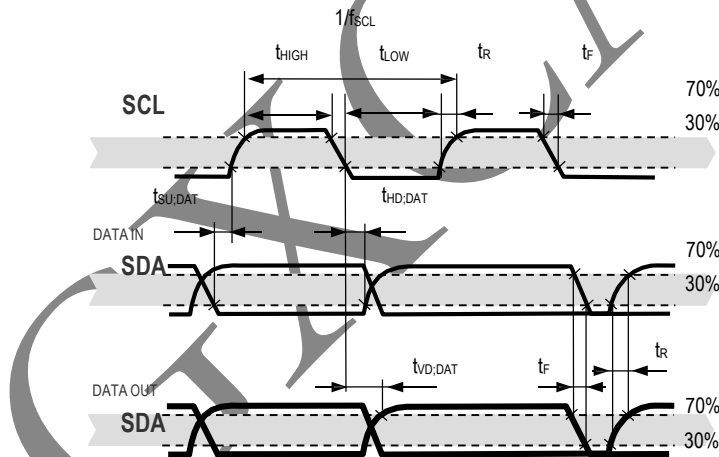
<sup>12</sup> According to ANSI/ESD S5.3.1-2009; AEC-Q100-011.

### 3.2 Communication Timings

Default conditions of 25 °C and 3.3 V supply voltage apply to values in the table below, unless otherwise stated.

| Parameter                                  | Symbol       | Conditions  | Standard-mode |      | Fast-mode                   |      | Fast-mode Plus              |      | Units   |
|--|--------------|---|---------------|------|-----------------------------|------|-----------------------------|------|---------|
|  |              |   | Min.          | Max. | Min.                        | Max. | Min.                        | Max. |         |
| SCL clock frequency                        | $f_{SCL}$    | -   | 0             | 100  | 0                           | 400  | 0                           | 1000 | kHz     |
| Hold time (repeated) START condition       | $t_{HD,STA}$ | After this period, the first clock pulse is generated | 4.0           | -    | 0.6                         | -    | 0.26                        | -    | $\mu s$ |
| LOW period of the SCL clock                | $t_{LOW}$    | -   | 4.7           | -    | 1.3                         | -    | 0.5                         | -    | $\mu s$ |
| HIGH period of the SCL clock               | $t_{HIGH}$   | -   | 4.0           | -    | 0.6                         | -    | 0.26                        | -    | $\mu s$ |
| Set-up time for a repeated START condition | $t_{SU,STA}$ | -   | 4.7           | -    | 0.6                         | -    | 0.26                        | -    | $\mu s$ |
| SDA hold time                              | $t_{HD,DAT}$ | -   | 0             | -    | 0                           | -    | 0                           | -    | $\mu s$ |
| SDA set-up time                            | $t_{SU,DAT}$ | -   | 250           | -    | 100                         | -    | 50                          | -    | ns      |
| SCL/SDA rise time                          | $t_R$        | -   | -             | 1000 | 20                          | 300  | -                           | 120  | ns      |
| SCL/SDA fall time                          | $t_F$        | -   | -             | 300  | $20 \times (V_{DD} / 5.5V)$ | 300  | $20 \times (V_{DD} / 5.5V)$ | 120  | ns      |
| SDA valid time                             | $t_{VD,DAT}$ | -   | -             | 3.45 | -                           | 0.9  | -                           | 0.45 | $\mu s$ |
| Set-up time for STOP condition             | $t_{SU,STO}$ | -   | 4.0           | -    | 0.6                         | -    | 0.26                        | -    | $\mu s$ |
| Capacitive load on bus line                | $C_B$        | -   | -             | 400  | -                           | 400  | -                           | 550  | pF      |

**Table 6** Communication timing specifications. The numbers above are values according to the I<sup>2</sup>C specification.



**Figure 5** Timing diagram for digital input/output pads. SDA directions as seen from the sensor. Bold SDA lines are controlled by the sensor, plain SDA lines are controlled by the micro-controller. Note that SDA valid read time is triggered by falling edge of preceding toggle.

## 4 Interface Specifications

The GXHTC3 supports I<sup>2</sup>C Normal, Fast Mode and Fast Mode Plus (SCL clock frequency from 0 to 1 MHz) with clock stretching. Please choose the protocol most suited to your application and refer to its specific specifications. For detailed information on the I<sup>2</sup>C protocol, refer to NXP I<sup>2</sup>C-bus specification and user manual UM10204, Rev. 6, April 4<sup>th</sup>, 2014.

The GXHTC3 comes in a 6-pin package – see Table 7.

|     |         |                             |
|-----|---------|-----------------------------|
| 1   | SDA     | Serial data, bidirectional  |
| 3   | SCL     | Serial clock, bidirectional |
| 4   | VDD     | Supply voltage              |
| 6   | GND     | Ground                      |
| 2,5 | No used |                             |

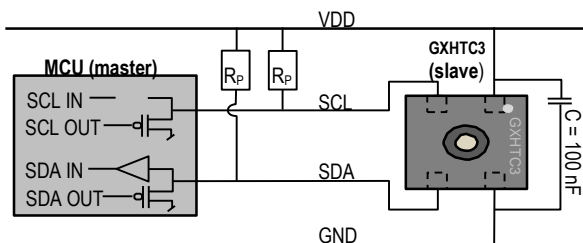
**Table 7** GXHTC3 pin assignment (top view).

Power-supply pins supply voltage (VDD) and ground (VSS) must be decoupled with a 100 nF capacitor that shall be placed as close to the sensor as possible – see Figure 6.

SCL is used to synchronize the communication between the microcontroller and the sensor. The master must keep the clock frequency within 0 to 1 MHz as specified in Table 6. The GXHTC3 may pull down the SCL line when clock stretching is enabled.

The SDA pin is used to transfer data in and out of the sensor. For safe communication, the timing specifications defined in the I<sup>2</sup>C manual must be met.

To avoid signal contention, the microcontroller must only drive SDA and SCL low. External pull-up resistors (e.g. 10 kΩ) are required to pull the signal high. For dimensioning resistor sizes please take the bus capacity requirements into account. Note that pull-up resistors may be included in I/O circuits of microcontrollers.



**Figure 6** Typical application circuit, including pull-up resistors  $R_p$  and decoupling of VDD and VSS by a capacitor.

For good performance of the GXHTC3 in the application, the center pad of the GXHTC3 offers the best thermal contact to the temperature sensor.

For more information on design-in, please refer to the document “GXHT3X Design Guide”.

For mechanical reasons the center pad should be soldered. Electrically, the center pad is internally connected to GND and may be connected to the GND net on the PCB additionally.

## 5 Operation and Communication

All commands and memory locations of the GXHTC3 are mapped to a 16-bit address space which can be accessed via the I<sup>2</sup>C protocol.

### 5.1 I<sup>2</sup>C Address

The I<sup>2</sup>C device address is given Table 8:

| GXHTC3                   | Hex. Code | Bin. Code |
|--------------------------|-----------|-----------|
| I <sup>2</sup> C address | 0x60      | 011'0000  |

**Table 8** GXHTC3 I<sup>2</sup>C device addr.

Each transmission sequence begins with START condition (S) and ends with an (optional) STOP condition (P) as described in the I<sup>2</sup>C-bus specification.

### 5.2 Power-Up, Sleep, Wakeup

Upon VDD reaching the power-up voltage level  $V_{POR}$ , the GXHTC3 enters the idle state after a duration of  $t_{PU}$ . After that, the sensor should be set to sleep mode with the command given in Table 9.

| Command | Hex. Code | Bin. Code           |
|---------|-----------|---------------------|
| Sleep   | 0xB098    | 1011'0000'1001'1000 |

**Table 9** Sleep command of the sensor.

When the sensor is in sleep mode, it requires the following wake-up command before any further communication, see Table 10:

| Command | Hex. Code | Bin. Code           |
|---------|-----------|---------------------|
| Wakeup  | 0x3517    | 0011'0101'0001'0111 |

**Table 10** Wake-up command of the sensor.

### 5.3 Measurement Commands

The GXHTC3 provides a clock-stretching option and the order of the signal return can be selected. These parameters are selected by dedicated measurement commands as summarized in Table 11. N. B.: Each measurement command triggers always both, a temperature *and* a relative humidity measurement.

### 5.4 Measuring and Reading the Signals

Each measurement cycle contains a set of four commands, each initiated by the I2C START condition and ended by the I2C STOP condition:

1. Wakeup command
2. Measurement command
3. Read out command
4. Sleep command

|              | Clock Stretching Enabled |               | Clock Stretching Disabled |               |
|--------------|--------------------------|---------------|---------------------------|---------------|
|              | Read T First             | Read RH First | Read T First              | Read RH First |
| Normal Mode  | 0x7CA2                   | 0x5C24        | 0x7866                    | 0x58E0        |
| Low Power M. | 0x6458                   | 0x44DE        | 0x609C                    | 0x401A        |

Table 11 Measurement commands.

An exemplary measurement set is shown in Figure 7

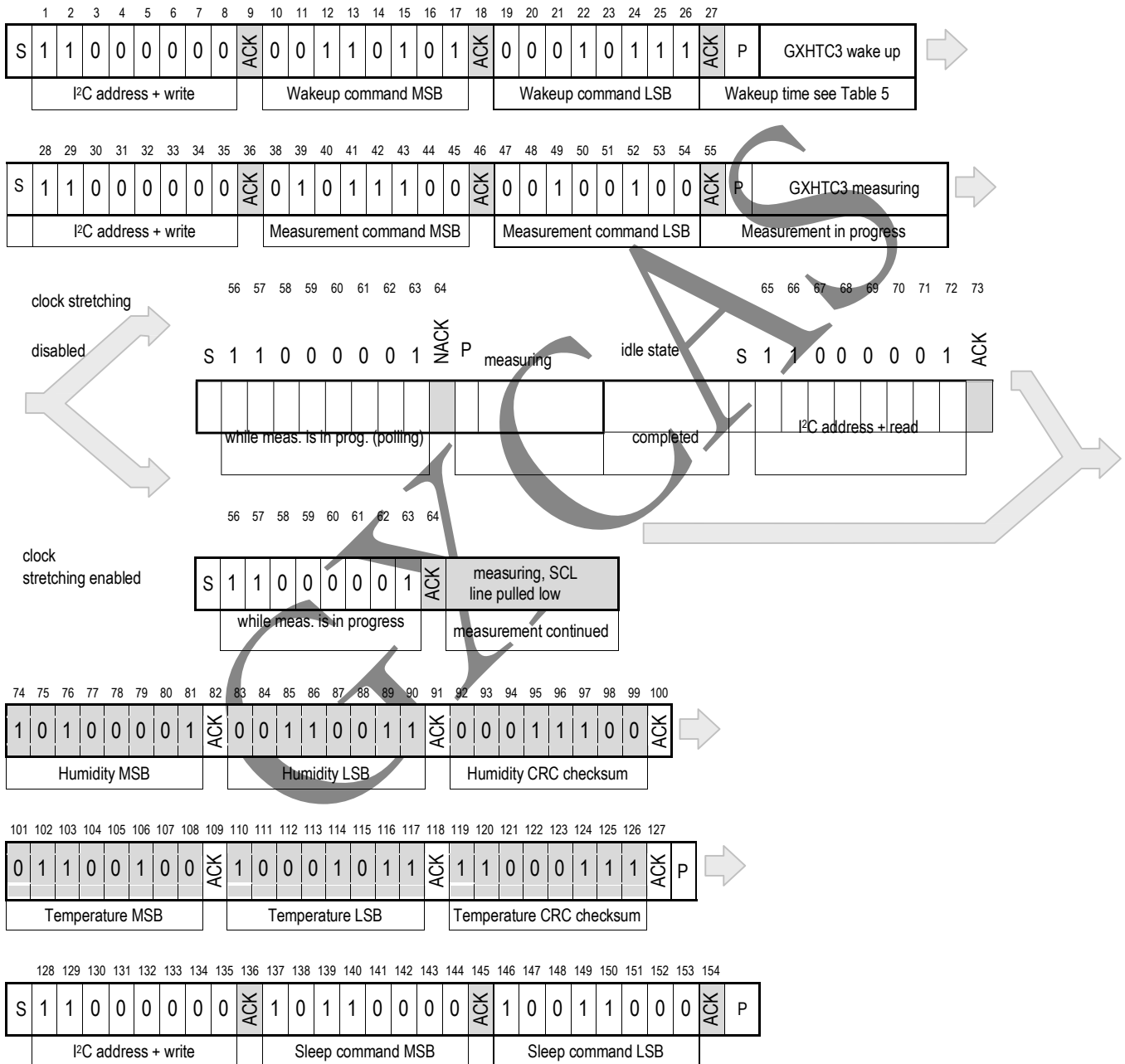


Figure 7 Communication sequence for waking up the sensor, starting a measurement and reading measurement results displaying both clock stretching options.

The numerical example corresponds to a read humidity-first command with clock stretching enabled. The physical values of the transmitted measurement results are 63 %RH and 23.7 °C. Clear blocks are controlled by the microcontroller, grey blocks by the GXHTC3.



**5.5 Sensor Behavior during Measurement and Clock Stretching**

In general, the sensor does not respond to any I<sup>2</sup>C activity during measurement, i.e. I<sup>2</sup>C read and write headers are not acknowledged (NACK). However, when clock stretching has been enabled by using a corresponding measurement command, the sensor responds to a read header with an ACK and subsequently pulls down the SCL line until the measurement is complete. As soon as the measurement is complete, the sensor starts sending the measurement results.

During measurement, the sensor has a current consumption according to Table 3.

For best possible repeatability of humidity and temperature measurements, it is recommended to avoid any communication on the I<sup>2</sup>C bus while GXHTC3 is measuring. For more information, see the application note “Optimization of Repeatability”.

**5.6 Readout of Measurement Results**

After a measurement command has been issued and the sensor has completed the measurement, the master can read the measurement results by sending a START condition followed by an I<sup>2</sup>C read header. The sensor will acknowledge the reception of the read header and send two bytes of data followed by one byte CRC checksum and another two bytes of data followed by one byte CRC checksum. Each byte must be acknowledged by the microcontroller with an ACK condition for the sensor to continue sending data. If the GXHTC3 does not receive an ACK from the master after any byte of data, it will not continue sending data.

The I<sup>2</sup>C master can abort the read transfer with a NACK condition after any data byte if it is not interested in subsequent data, e.g. the CRC byte or the second measurement result, in order to save time.

In case the user needs humidity and temperature data but does not want to process CRC data, it is recommended to read the first two bytes of data with the CRC byte (without processing the CRC data) and abort the read transfer after reading the second two data bytes with a NACK. This procedure is more time efficient than starting two different measurements and aborting the read transfer after the first two data bytes each time.

**5.7 Soft Reset**

The GXHTC3 provides a soft reset mechanism that forces the system into a well-defined state without removing the power supply. If the system is in its idle state (i.e. if no measurement is in progress) the soft reset command can be sent to GXHTC3 according to Table 12. This triggers the

sensor to reset all internal state machines and reload calibration data from the memory.

| Command        | Hex. Code | Bin. Code           |
|----------------|-----------|---------------------|
| Software reset | 0x805D    | 1000'0000'0101'1101 |

**Table 12** Soft reset command.

**5.8 Reset through General Call**

Additionally, a reset of the sensor can also be generated using the “general call” mode according to I<sup>2</sup>C-bus specification<sup>14</sup>. This generates a reset which is functionally identical to using the nReset pin. It is important to understand that a reset generated in this way is not device specific. All devices on the same I<sup>2</sup>C bus that support the general call mode will perform a reset. Additionally, this command only works when the sensor is able to process I<sup>2</sup>C commands. The appropriate command consists of two bytes and is shown in Table 13.

| Command                                      | Code   |
|--|--------|
| Address byte                                 | 0x00   |
| Second byte                                  | 0x06   |
| Reset command using the general call address | 0x0006 |

**Table 13** Reset through the general call address (clear blocks are controlled by the microcontroller, grey blocks by the sensor)

**5.9 Read-out of ID Register**

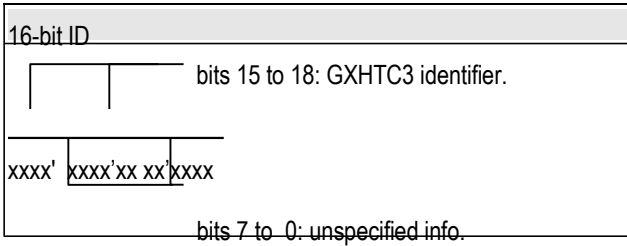
The GXHTC3 has an ID register which contains an GXHTC3- specific product code. The read-out of the ID register can be used to verify the presence of the sensor and proper communication. The command to read the ID register is shown in Table 14.

| Command          | Hex. Code | Bin. Code           |
|------------------|-----------|---------------------|
| Read ID register | 0xEFC8    | 1110'1111'1100'1000 |

**Table 14** Read-out command of ID register.

It needs to be sent to the GXHTC3 after an I<sup>2</sup>C write header. Once the GXHTC3 has acknowledged the proper reception of the command, the master can send an I<sup>2</sup>C read header and the GXHTC3 submits the 16-bit ID followed by 8 bits of CRC. The structure of the ID is described in Table 15.





**Table 15** Structure of the 16-bit ID

### 5.10 Checksum Calculation

The 8-bit CRC checksum transmitted after each data word is generated by a CRC algorithm with the properties displayed in Table 16. The CRC covers the contents of the two previously transmitted data bytes.

| Property       | Value                                    |
|----------------|--|
| Name           | CRC-8                                    |
| Width          | 8 bits                                   |
| Polynomial     | 0x31 ( $x^8 + x^5 + x^4 + 1$ )           |
| Initialization | 0xFF                                     |
| Reflect input  | False                                    |
| Reflect output | False                                    |
| Final XOR      | 0x00                                     |
| Examples       | CRC (0x00) = 0xAC<br>CRC (0xBEEF) = 0x92 |

**Table 16** GXHTC3 CRC properties.

### 5.11 Conversion of Sensor Output

Measurement data is always transferred as 16-bit values. These values are already linearized and temperature compensated by the GXHTC3. Humidity and temperature values can be calculated with the formulas in given below.

Relative humidity conversion formula (result in %RH):

$$RH = 100 \cdot \frac{S_{RH}}{2^{16}}$$

Temperature conversion formula (result in °C):

$$T = -45 + 175 \cdot \frac{S_T}{2^{16}}$$

$S_{RH}$  and  $S_T$  denote the raw sensor output (as decimal values) for humidity and temperature, respectively.

## 6 Quality

### 6.1 Environmental Stability

Qualification of the GXHTC3 is performed based on the JEDEC JESD47 qualification test method.

## 6.2 Material Contents

The device is fully RoHS, REACH and Halogen-Free

GXHTC3 sensors are provided in a DFN package with an outline of  $2 \times 2 \times 0.75 \text{ mm}^3$  and a terminal pitch of 1 mm. DFN stands for dual flat no leads. The humidity sensor opening is centered on the top side of the package.

The sensor chip is made of silicon and is mounted to a lead frame. The latter is made of Cu plated with Ni/Pd/Au. Chip and lead frame are overmolded by an epoxy-based mold compound. Please note that the sidewalls of sensor are diced and therefore these diced lead frame surfaces are not covered with the respective plating.

The Moisture Sensitivity Level classification of the GXHTC3 is MSL1, according to IPC/JEDEC J-STD-020.

All GXHTC3 sensors are laser marked for easy identification and traceability. The marking on the sensor consists of two lines and a pin-1 indicator. The top line contains the sensor type (GXHTC3), the bottom line contains a 5-digit alphanumeric tracking code. The pin-1 indicator is located in the top left corner. See Figure 8 for illustration.



**Figure 8** Laser marking on GXHTC3, the top line with the pin-1 indicator and the sensor type, the bottom line with the 5-digit alphanumeric tracking code.

Reels are also labeled and provide additional traceability information.

## 8 Ordering Information

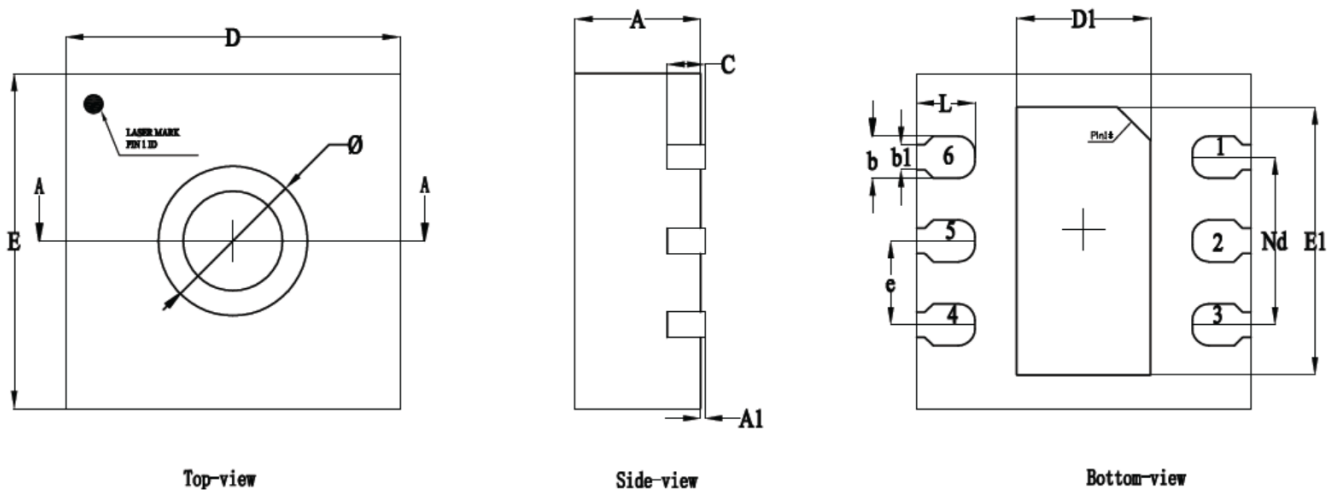
The GXHTC3 can be ordered in tape and reel packaging with different sizes, see Table 17. The reels are sealed into antistatic ESD bags. A drawing of the packaging tape with sensor orientation is shown in Figure 11.

| Quantity | Packaging   | Reel Diameter   | Order Number |
|----------|-------------|-----------------|--------------|
| 2500     | Tape & Reel | 180 mm (7 inch) | 3.000.047    |

**Table 17** GXHTC3 ordering option.

**9 Technical Drawings**

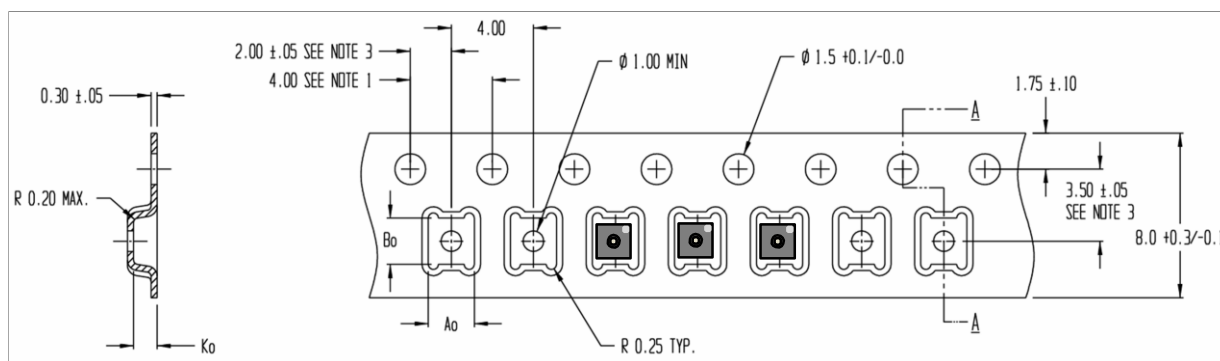
**9.1 Package Outline**



| SYMBOL        | MILLIMETER |      |      |
|---------------|------------|------|------|
|               | MIN        | NOM  | MAX  |
| A             | 0.70       | 0.75 | 0.80 |
| A1            | —          | 0.02 | 0.05 |
| b             | 0.20       | 0.25 | 0.30 |
| b1            | —          | 0.15 | —    |
| L             | 0.30       | 0.35 | 0.40 |
| c             | 0.203 REF  |      |      |
| D             | 1.90       | 2.00 | 2.10 |
| E             | 1.90       | 2.00 | 2.10 |
| D1            | 0.60       | 0.70 | 0.80 |
| E1            | 1.50       | 1.60 | 1.70 |
| Nd            | 1.0 BSC    |      |      |
| e             | 0.50 BSC   |      |      |
| $\varnothing$ | 0.70       | 0.80 | 0.90 |
| h             | —          | 0.29 | —    |

**Figure 9** Package outline drawing of the GXHTC3. Dimensions are given in millimeters.

## 9.2 Tape and Reel Package



SECTION A - A

$A_o = 2.25$   
 $B_o = 2.25$   
 $K_o = 1.15$

TOLERANCES - UNLESS  
 NOTED 1PL ±.2 2PL ±.10

NOTES:

1. 10 SPROCKET HOLE PITCH CUMULATIVE TOLERANCE ±0.2
2. CAMBER IN COMPLIANCE WITH EIA 481
3. POCKET POSITION RELATIVE TO SPROCKET HOLE MEASURED AS TRUE POSITION OF POCKET, NOT POCKET HOLE
4.  $A_o$  AND  $B_o$  ARE CALCULATED ON A PLANE AT A DISTANCE "R" ABOVE THE BOTTOM OF THE POCKET.

**Figure 11** Technical drawing of the packaging tape with sensor orientation in tape. Header tape is to the right and trailer tape to the left on this drawing. Dimensions are given in millimeters.

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