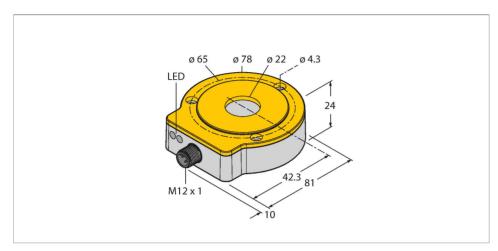


# RI360P0-QR24M0-ELIU5X2-H1151 Contactless Encoder - Analog Premium Line



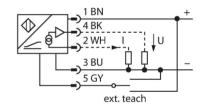
# Technical data

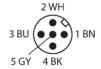
_		
Type	RI360P0-QR24M0-ELIU5X2-H1151	
ldent. no.	1590908	
Measuring principle	Inductive	
Max. Rotational Speed	12000 rpm	
	Determined with standardized construction, with a steel shaft $\emptyset$ 20 mm, L = 50 mm and reducer $\emptyset$ 20 mm	
Starting torque shaft load (radial / axial)	not applicable, because of contactless measuring principle	
Resolution	16 bit	
Measuring range	0360°	
Nominal distance	1.5 mm	
Repeat accuracy	≤ 0.01 % of full scale	
Linearity deviation	≤ 0.05 %f.s.	
Temperature drift	$\leq$ ± 0.004 % / K	
Ambient temperature	-25+85 °C	
Operating voltage	1530 VDC	
Residual ripple	≤ 10 % U <sub>ss</sub>	
Isolation test voltage	≤ 0.5 kV	
Short-circuit protection	yes	
Wire breakage/Reverse polarity protection	yes / yes (voltage supply)	
Output type	absolute singleturn	
Resolution singleturn	16 Bit	
Output function	5-pin, Analog output	

# **Features**

- Compact, rugged housing
- Many mounting possibilities
- Status displayed via LED
- Measuring range indicated via LED
- Immune to electromagnetic interference
- Measuring range programmable via Easy Teach
- Output signal programmable via Easy Teach
- Resolution, 16-bit
- 15...30 VDC
- 0...10 V and 4...20 mA
- Male M12 x 1, 5-pin

# Wiring diagram





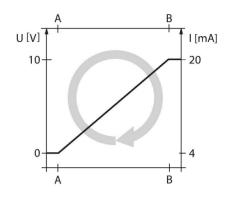
Functional principle

The measuring principle of inductive angle sensors is based on oscillation circuit coupling between the positioning element and the sensor, whereby an output signal is provided proportional to the angle of the positioning element. The rugged sensors are wear and maintenance-free, thanks to the contactless operating principle. They convince through their excellent repeatability, resolution and linearity within a broad temperature range. The innovative technology ensures a high immunity to electromagnetic DC and AC fields.



# Technical data

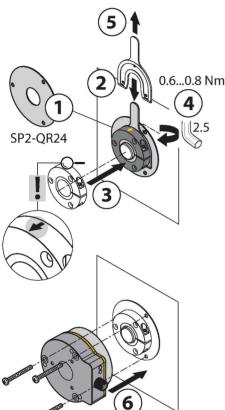
Voltage output	010 V	
Current output	420 mA	
Diagnostic	Positioning element not within detection range: Output signal 24mA or 11 V	
Load resistance voltage output	≥ 4.7 kΩ	
Load resistance, current output	≤ 0.4 kΩ	
Sample rate	5000 Hz	
Current consumption	< 50 mA	
Design	QR24	
Dimensions	81 x 78 x 24 mm	
Flange type	Flange without mounting element	
Shaft Type	Hollow shaft	
Shaft diameter D [mm]	6 6.35 9.525 10 12 12.7 14 15.875 19.05	
Housing material	Metal/plastic, ZnAlCu1/PBT-GF30-V0	
Electrical connection	Connector, M12 $\times$ 1	
Vibration resistance	55 Hz (1 mm)	
Vibration resistance (EN 60068-2-6)	20 g; 103000 Hz; 50 cycles; 3 axes	
Shock resistance (EN 60068-2-27)	100 g; 11 ms ½ sinus; each 3x; 3 axes	
Continuous shock resistance (EN 60068-2-29)	40 g; 6 ms ½ sinus; each 4000 x; 3 axes	
Protection class	IP68 / IP69K	
MTTF	138 years acc. to SN 29500 (Ed. 99) 40 °C	
Power-on indication	LED, Green	
Measuring range display	LED, yellow, yellow flashing	



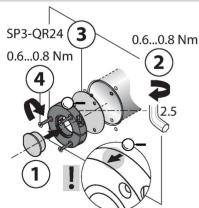


# Mounting instructions

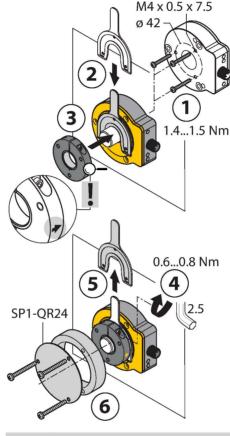
### Mounting instructions/Description



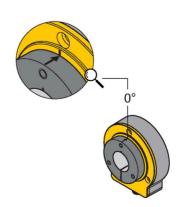








Default: 0°



Extensive range of mounting accessories for easy adaptation to many different shaft diameters. Based on the functional principle of RLC coupling, the sensor operates absolutely wear-free and is immune to magnetized metal splinters and other interference fields. Wrong installation is hardly

The adjacent figure shows the two separate units, sensor and positioning element.

### Mounting option A:

First, interconnect positioning element and rotatable shaft. Then place the encoder above the rotating part in such a way that you get a tight and protected unit

### Mounting option B:

Push the encoder on the back site of the shaft and fasten it to the machine. Then clamp the positioning element to the shaft with the bracket.

### Mounting option C:

If the positioning element is to be screwed on a rotating machine part, use the RAO-QR24 plug which is included in the delivery. Then tie up the bracket. Screw on the encoder via the three bores.

The separately arranged sensor and positioning element inhibit that compensating currents or damaging mechanical loads are transmitted via the shaft to the sensor. In addition, the encoder remains tight and highly protected during its entire

The accessories enclosed in the delivery help to mount encoder and positioning element at an optimal distance from each other. LEDs indicate the switching status.

optimal distance from each other. LEDs indicate the switching status.

Status display via LED green steady:
Optimal sensor supply yellow steady:
Positioning element has reached the end of the measuring range. This is indicated by a lower signal quality.
yellow flashing:
Positioning element is outside the measuring range.

off:
Positioning element is in the measuring range.

Bridge between teach input Pin 5 (GY)	Gnd Pin 3 (BU)	Ub Pin1 (BN)	LED
2 s	Start value	End value	Status LED flashes then turns steady after 2 s
10 s	CCW rotation, then return to last preset value	CW rotation, then return to last preset value	After 10 s status LED flashes fast for 2 s
15 s	-	Factory setting (360°, CW)	after 15 s power and status LED alternate

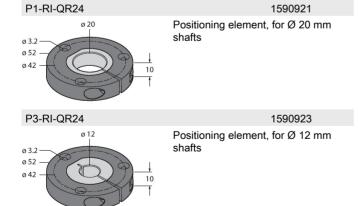
To avoid unintended teaching, keep pin 5 potential-free.

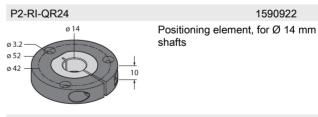
Preset Parameterization (Teaching without Positioning Flement)

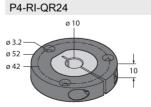
Bridge pin between teach input Pin 5 (GY)	Gnd Pin 3 (BU)	Ub Pin 1 (BN)	LED
2 s	Activate selection mode for output signal (for 10 s)	Activate preset mode (for 10 s)	Status LED steady, flashes after 2 s
10 s	CCW rotation direction	CW rotation direction	After 10 s status LED flashes fast for 2 s
15 s		Factory setting (360°, CW)	After 15 s power and status LED flash equally fast
Output configuration	Gnd Pin 3 (BU)		Status LED
I out: 420 mA	Press once		1 x flashing
l out: 020 mA	Press twice		2 x flashing
Uout: 010 V	Press three times		3 x flashing
Uout: 05 V	Press four times		4 x flashing
Uout: 0.5 V / 4.5 V	Press five times		5 x flashing
Preset mode / Angular range		Ub Pin 1 (BN)	Status LED
45°		Press once	1 x flashing
60°		Press twice	2 x flashing
90°		Press three times	3 x flashing
180°		Press four times	4 x flashing
270°		Press five times	5 x flashing

To avoid unintended teaching, keep pin 5 potential-free.

## Accessories







1590924 Positioning element, for Ø 10 mm shafts

1590922

# TURCK

